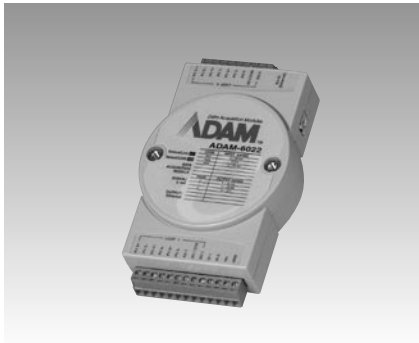


# ADAM-6022

# ADAM-6000

Ethernet-based Dual-loop PID Controller

## Series Dimensions



ADAM-6022

CE FCC

### Specifications

#### General

- **Dimensions (W x H x D)** 70 x 112 x 25 mm
- **Loop Number** 2 (3 AI, 1 AO, 1 DI, 1 DO for each control loop)
- **Power Consumption** 4 W (typical)
- **LAN** 10/100Base-T

#### Analog Input

- **Accuracy**  $\pm 0.1\%$  or better
- **Bandwidth** 13.1 Hz @ 50 Hz  
15.72 Hz @ 60 Hz
- **Channels** 6 differential
- **CMR @ 50/60 Hz** 92 dB min.
- **Resolution** 16 bits
- **Input Impedance** 20 M $\Omega$
- **Input Range** 0 ~ 10 V<sub>DC</sub>; 0 ~ 20 mA,  
4 ~ 20 mA
- **Isolation Voltage** 2,000 V<sub>DC</sub>
- **Sampling Rate** 10 samples/sec.
- **Span Drift**  $\pm 25$  ppm/ $^{\circ}$ C
- **Zero Drift**  $\pm 6$   $\mu$ V/ $^{\circ}$ C

#### Analog Output

- **Accuracy** 0.05% of FSR
- **Channels** 2
- **Drift**  $\pm 50$  ppm/ $^{\circ}$ C
- **Drive Voltage** 15 V<sub>DC</sub> (current output)
- **Isolation Voltage** 2,000 V<sub>DC</sub>
- **Output Range** 0 ~ 10 V<sub>DC</sub>; 4 ~ 20 mA,  
0 ~ 20 mA
- **Resolution** 12 bits

#### Digital Inputs

- **Channels** 2
- **Dry Contact:** Logic level 0: close to GND  
logic level 1: open
- **Wet Contact:** Logic level 0: +3V<sub>max</sub>  
Logic level 1: 10~30 V<sub>DC</sub>

#### Digital Outputs

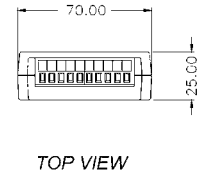
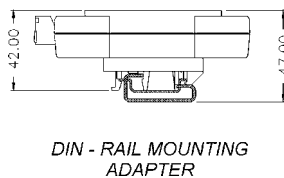
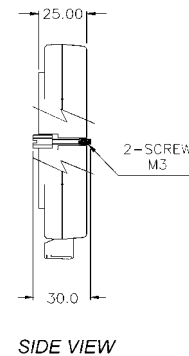
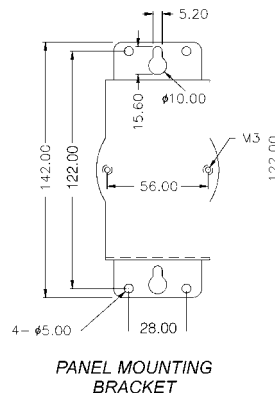
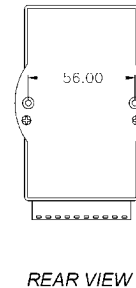
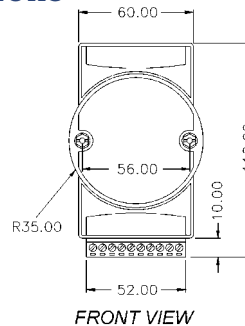
- **Channels** 2
- **Open Collector to 30 V**  
100 mA max. load

#### Environment

- **Humidity (Operating)** 20~95% RH, (non-cond)
- **Humidity (Storage)** 0~95% RH, (non-cond.)
- **Operating Temperature** -10~50 $^{\circ}$ C
- **Storage Temperature** -20~80 $^{\circ}$ C

### Dimensions

Unit: mm



### Ordering Information

- **ADAM-6022** Dual-loop PID Controller

### Software Ordering Information

- **PCLS-OPC/MTP** Modbus/TCP OPC Server
- **AStudio-WNT/DEV** Astudio-WNI/PRO Web-enabled HMI/SCADA Software